

Development of a massive parallel and optimized phase-field solver for the sinter process

J. Hötzer, H. Hierl, F. Hafner, M. Seiz, L. Promberger, C. Seer, M. Kellner, W. Rheinheimer, M. Berghoff, B. Nestler

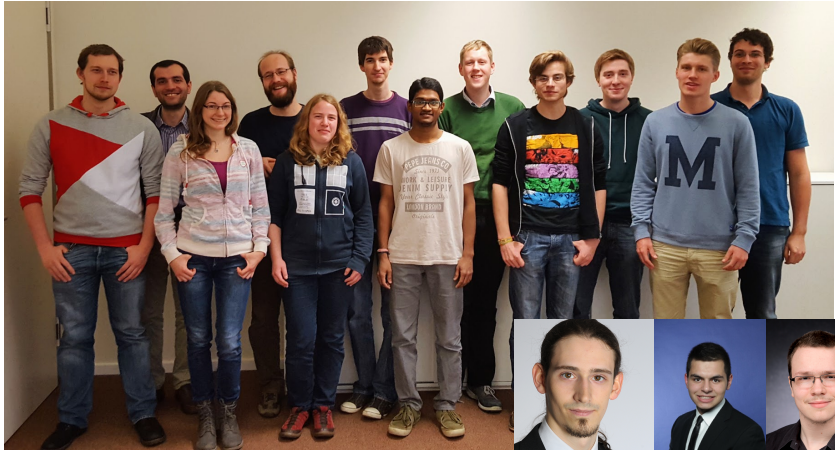
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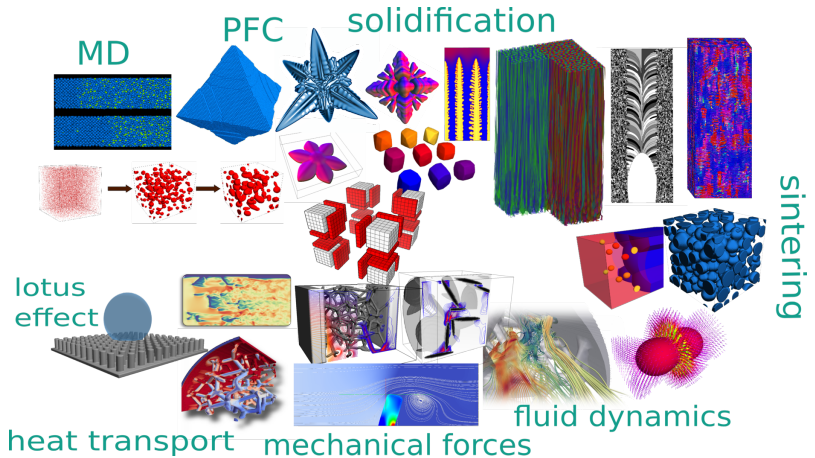
Contents:

- Motivation
- Phase-field model
- Code Optimization
- Performance results
- Simulation results

Group - High Performance Materials Computing and Data Science



Overview



Reality/Experiments

Physical Parameter

Mathematical Model

Numerical Scheme

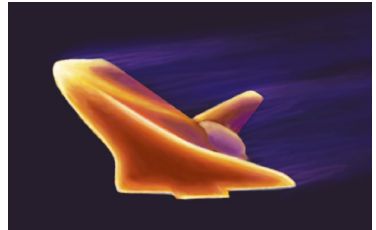
Application Program

Parallel Programming Models
(OpenMP, MPI, OpenCl)

Hardware Architecture

Applications of ceramics

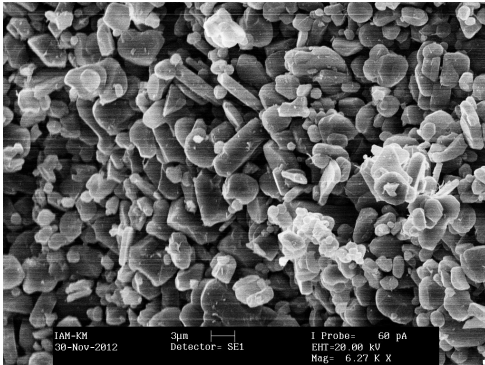
- everyday items (e.g. plates, cups) are “simple” to produce
- however high performance materials
 - sensors (e.g oxygen)
 - spark plugs
 - artificial hip joint
 - batteries
 - electronics
 - ...
- require a tailored microstructure with defined properties
- microstructure is directly influenced by various process and material properties



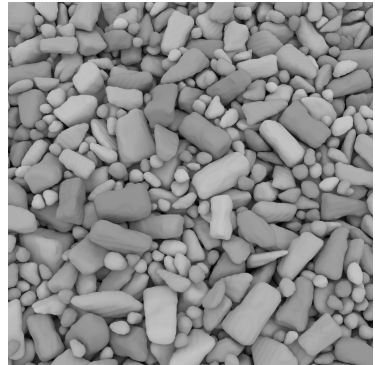
<https://upload.wikimedia.org/wikipedia/commons/6/6a/Sparkplug.jpg>
<https://upload.wikimedia.org/wikipedia/commons/f/fd/Stsheat.jpg>

Initial structure - Green body

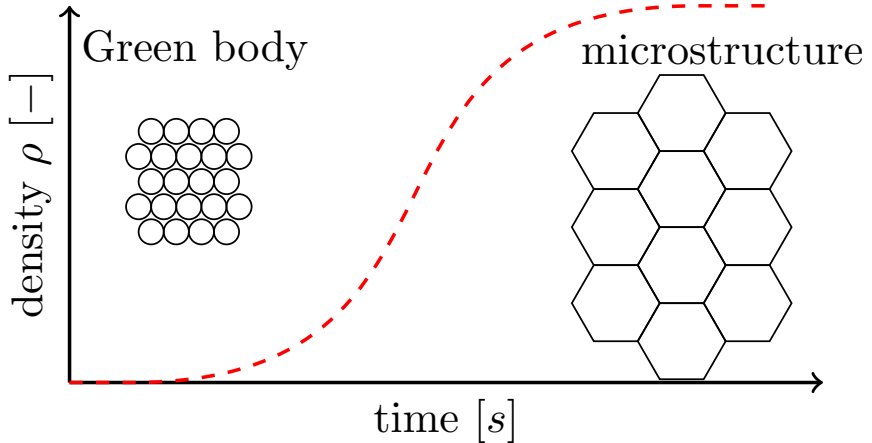
■ Experiment



■ Generated



experimental image: Fabian Lemke - IAM



Video: Experiment of the sinter process

- solid state sintering
- coupled phase-field and concentration model
- different diffusion paths
- number of grains/particles $N \gg 1000$ with size distribution
- large domain sizes ($> 500^3$ cells)
- large parameter matrices (N^2 , N^3)
- parallel PACE3D framework (MPI)

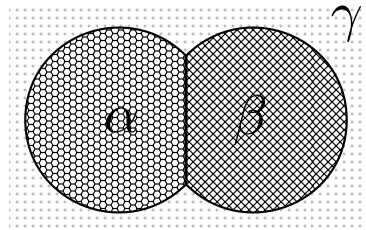


Phase-field model derivation

- total system energy (Laypounov functional)

$$\mathcal{L}(s_1, s_2, \dots) = \sum_{\substack{\beta=1 \\ \alpha < \beta}}^N \int_{\partial V_\alpha} \gamma_{\alpha\beta}(\vec{n}) dA_{\alpha\beta} + \sum_{\alpha=1}^N \int_{V_\alpha} f_{\text{bulk}}(s_1, s_2, \dots) dV_\alpha$$

- surface energy $\gamma_{\alpha\beta}$ in direction \vec{n}
- bulk energy of a “phase”



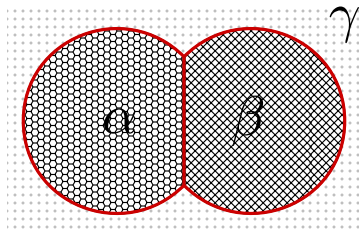
Choudhury, A., Nestler, B (2012). *Physical Review E*, 85 (2), 71(4), 021602

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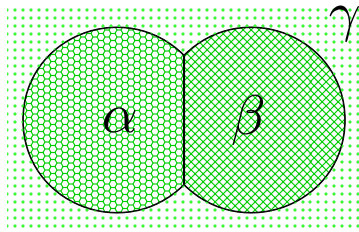
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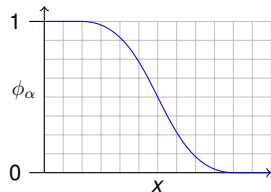
Choudhury, A., Nestler, B (2012). *Physical Review E*, 85 (2), 71(4), 021602

Phase-field model derivation

- Grand chemical potential functional:

$$\Psi(\phi, \mu, T) = \int_{\Omega} \underbrace{\left(\epsilon a(\phi, \nabla \phi) + \frac{1}{\epsilon} \omega(\phi) \right)}_{\text{surface energy}} + \underbrace{\psi(\phi, \mu, T)}_{\text{bulk potential}} d\Omega$$

- phase-field vector $\phi = (\phi_1, \phi_2, \dots, \phi_N)^T$
- order parameter ϕ_α represents the volume fraction of each phase
- volumetric interface at the surface
- smooth transition between the order parameters
- Allen-Cahn type variational differentiation of the functional
- → **no interface tracking needed**



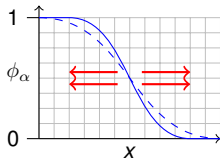
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- Gradient energy density



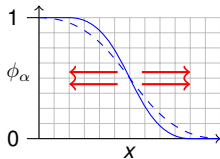
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Phase-field model derivation

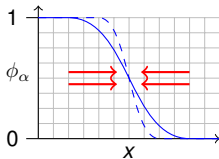
- Grand chemical potential functional:

$$\Psi(\phi, \mu, T) = \int_{\Omega} \left(\underbrace{\epsilon a(\phi, \nabla \phi)}_{\text{gradient energy density}} + \underbrace{\frac{1}{\epsilon} \omega(\phi)}_{\text{interfacial free energy density}} \right) + \underbrace{\psi(\phi, \mu, T)}_{\text{bulk potential}} d\Omega$$

- Gradient energy density



- Interfacial free energy density



Choudhury, A., Nestler, B (2012). *Physical Review E*, 85 (2), 71(4), 021602

Phase-field model derivation

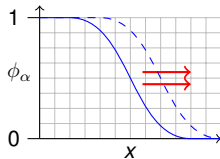
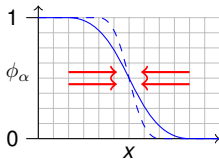
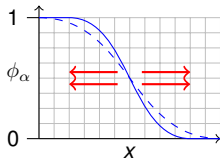
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- Gradient energy density

- Interfacial free energy density

- Bulk free energy density



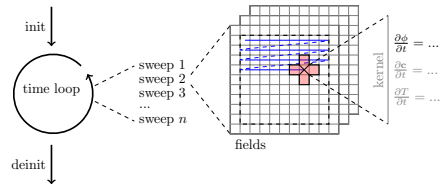
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Phase-field algorithm

- lattice fields
 - two AoS for phase-field (ϕ_{src} , ϕ_{dst})
 - two SoA for chemical potential (μ_{src} , μ_{dst})
- storing new values calculated from *src* in *dst*

Algorithm 1 calculation of one time step

- 1: $\phi_{dst} \leftarrow \phi\text{-kernel}(\phi_{src}, \mu_{src})$
- 2: $\mu_{dst} \leftarrow \mu\text{-kernel}(\mu_{src}, \phi_{src}, \phi_{dst})$
- 3: ϕ_{dst} -boundary conditions
- 4: μ_{dst} -boundary conditions
- 5: ϕ_{dst} , μ_{dst} -ghost layer exchange
- 6: **swap** $\phi_{src} \leftrightarrow \phi_{dst}$ and $\mu_{src} \leftrightarrow \mu_{dst}$



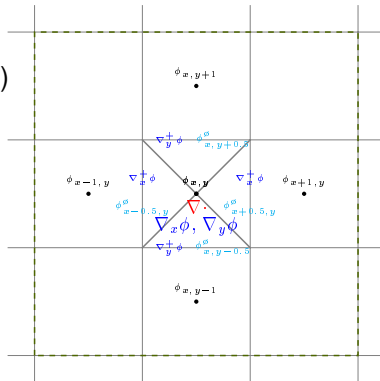
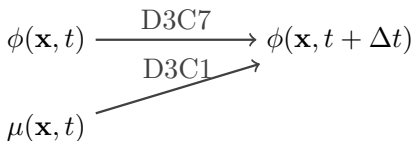
ϕ -kernel

$$\tau \varepsilon \frac{\partial \phi_\alpha}{\partial t} = - \underbrace{\varepsilon \left(\frac{\partial \mathbf{a}(\phi, \nabla \phi)}{\partial \phi_\alpha} + \nabla \cdot \frac{\partial \mathbf{a}(\phi, \nabla \phi)}{\partial \nabla \phi_\alpha} \right)}_{\text{D3C7}} \underbrace{- \frac{1}{\varepsilon} \frac{\partial \omega(\phi)}{\partial \phi_\alpha} - \frac{\partial \psi(\phi, \boldsymbol{\mu}, T)}{\partial \phi_\alpha}}_{\text{D3C1}} + \lambda$$

- finite differences scheme for space
- explicit Euler scheme for the time discretization
- roofline performance model:

FLOP/_{cell} (likwid) 893 / 7812 ($N = 4 / N = 8$)
 loads & stores 40 byte/phase

→ compute bound

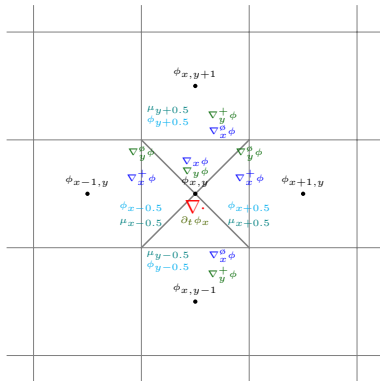
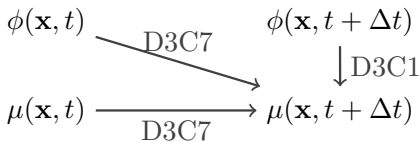


$$\frac{\partial \mu}{\partial t} = \underbrace{\left[\sum_{\alpha=1}^N h_{\alpha}(\vec{\phi}) \left(\frac{\partial \bar{c}^{\alpha}(\mu, T)}{\partial \mu} \right) \right]^{-1}}_{D3C1} \left(\underbrace{\nabla \cdot (\mathbf{M}(\vec{\phi}, \mu, T) \nabla \mu)}_{D3C7} - \underbrace{\sum_{\alpha=1}^N \bar{c}^{\alpha}(\mu, T) \frac{\partial h_{\alpha}(\phi)}{\partial t}}_{\alpha=1} - \underbrace{\sum_{\alpha=1}^N h_{\alpha}(\vec{\phi}) \left(\frac{\partial \bar{c}^{\alpha}(\mu, T)}{\partial T} \right) \frac{\partial T}{\partial t}}_{D3C1} \right)$$

- finite differences scheme for space
- explicit Euler scheme for the time discretization
- roofline performance model:

FLOP/cell 467
 loads & stores 144

→ compute bound



Optimizations layer

Parameter layer

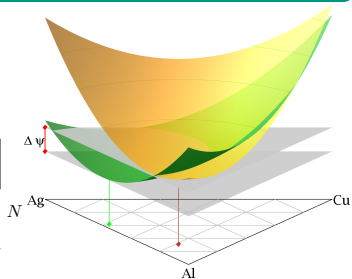
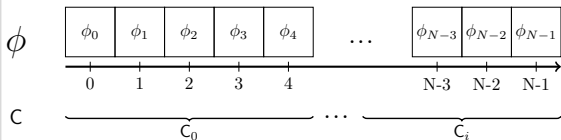
Model layer

Algorithm layer

Hardware layer

Parameter layer

- fitting of Gibbs energies with parabolic approach from CALPHAD databases to calculate the driving forces
- reduction of the parameter matrices with the size $N \times N$ and $N \times N \times N$ to a class based concept of 2×2 and $2 \times 2 \times 2$

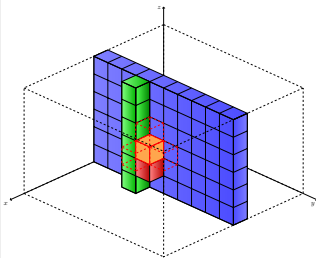


Model layer

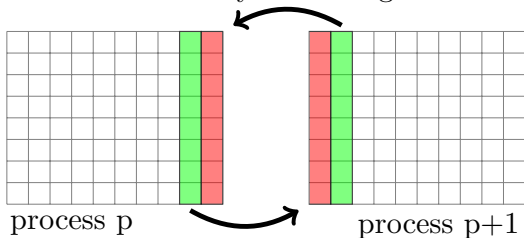
- simplifications due to defined setup (e.g. fix number of concentrations)
- classification of cells \longrightarrow skip terms
 $\partial_t \phi = \dots$ needs only calculated in the diffuse interface
- elimination and pre-calculation of common subexpressions (e.g. $1/2 \longrightarrow 0.5$)

Algorithm layer

- access patterns / stencils (streaming)
- domain decomposition (MPI)
- buffering of staggered values - point line plane buffer
- local reduction of order parameter (LROP) for ϕ

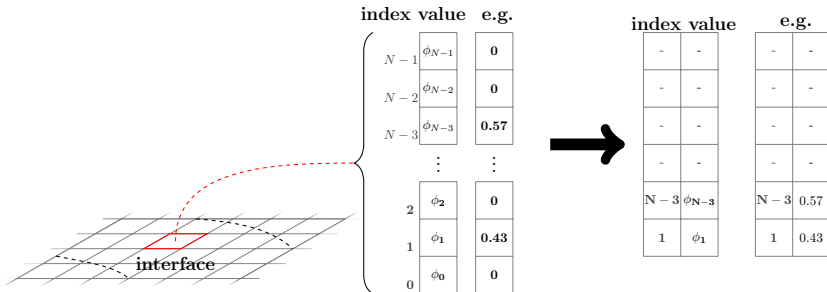


Ghost layer exchange



Local reduced order parameter (LROP)

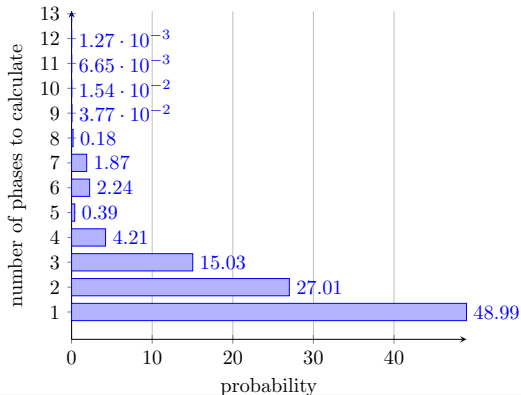
- in models **maximal six phases** in one cell enough
(Kim, Kim, Kim and Park, (2006), Physical Review E, 74, 061605)
- only **storage phase values** $\phi_\alpha \neq 0$ and their **index** in the phase-field vector ϕ instead of all N elements
- **other phases** are assumed to be **zero**
 - memory requirements independent from number of phases
 - reduction of calculation time $\sum_\alpha^N \dots \rightarrow \sum_\alpha^{\max(6)} \dots$



Hardware layer

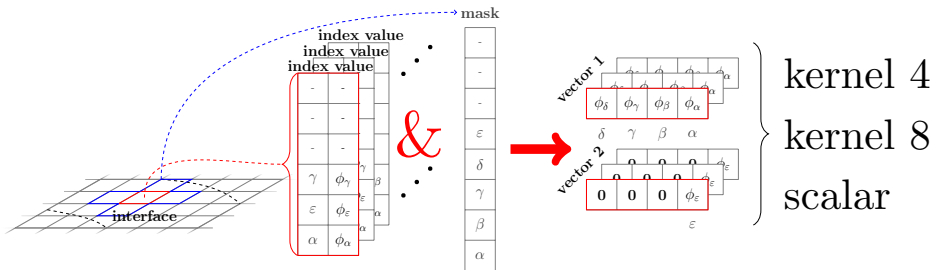
- **explicit** vectorization with SIMD **intrinsics**
- light weight macro layer to support **SSE** and **AVX**
- for $\partial_t \mu$ **classical approach**, calculate multiple cells at once
- for $\partial_t \phi$ the **calculation per cell is vectorized**
 - calculate multiple phases at once
 - still possible to use all optimizations (e.g. classification)
 - **LROP cells differ** between neighboring cells, but for **vectorization they need the same structure** which results in **complex sorting**
 - good experience with vectorization of four phases (**up to 25% peak performance**)

- many **vector matrix multiplications** of the form $\mathbf{y} = \sum \mathbf{A}\mathbf{x}$
- optimized **pattern approach** to pre-rotate all combinations of x for four and eight phases
- **three kernels** depending on the number of phases N to calculate in current cell
 - vectorized kernel for **4** phases
 - vectorized kernel for **8** phases
 - scalar kernel for **more** than eight phases

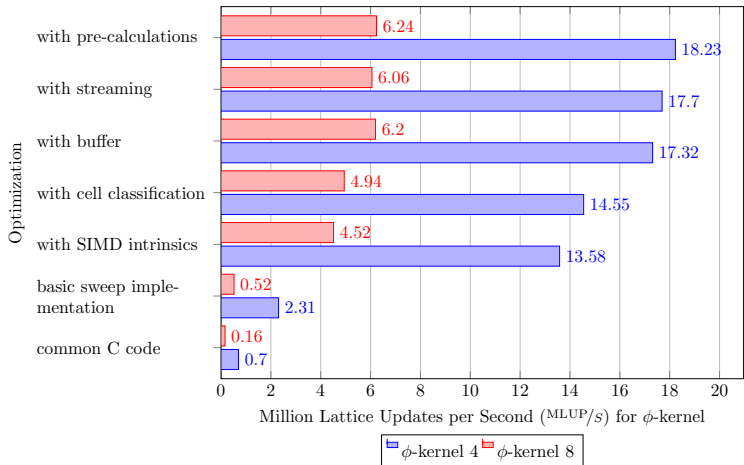


Vectorization

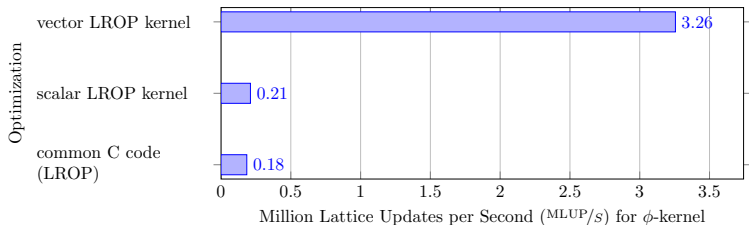
- mapping of **LROP cell** to **SIMD vector**
 - all local ϕ vectors of the stencil and matrices need the same order to calculate e.g. $\nabla\phi$
- create **mask** depending on stencil
- create **SSE/AVX vectors** from LROP cell **based on mask**
- depending on size of mask select the optimal kernel



Optimization results – ϕ -kernel 4 / 8 – Hazel Hen

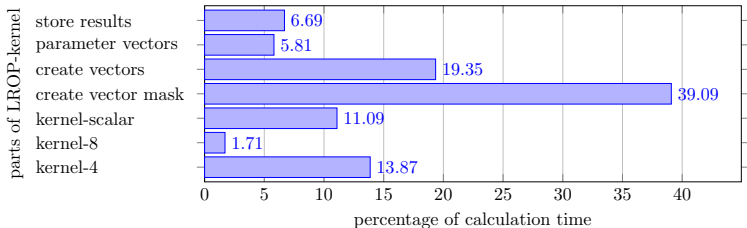


- $60 \times 60 \times 60$ cells per block
- only kernel without mapping from LROP to SSE/AVX vectors



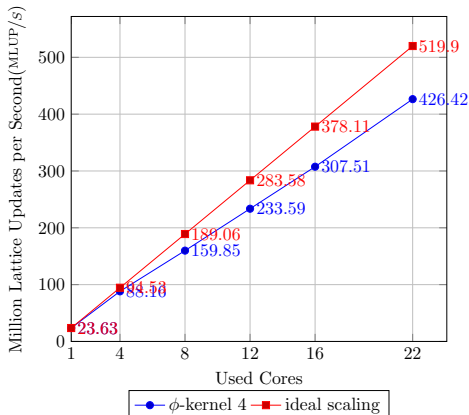
- preliminary results of LROP-kernel with mapping
- 17.9% to 52.2% of single ϕ -kernels

LROP-kernel analysis of typical simulation



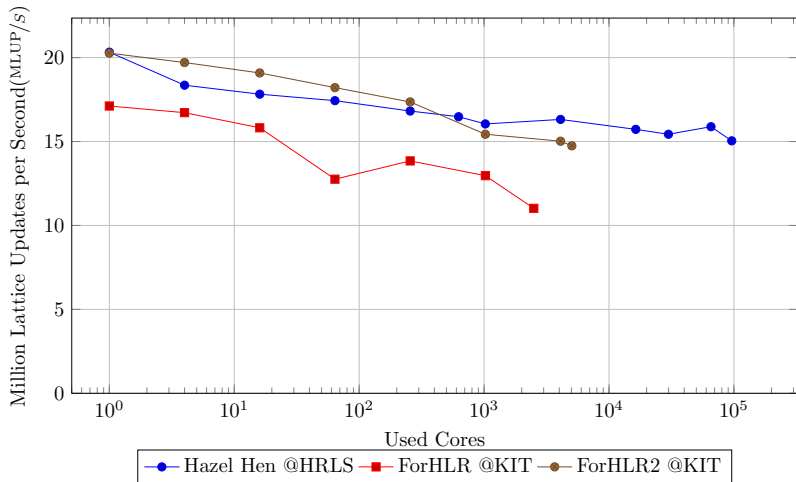
- preliminary results of LROP-kernel with mapping
- mapping from LROP cell to vectors requires 71.75 %
- calculation requires 27.48 %

Single node scaling – ϕ -kernel 4 – Hazel Hen



- preliminary results of ϕ -kernel 4
- $60 \times 60 \times 60$ cells per block

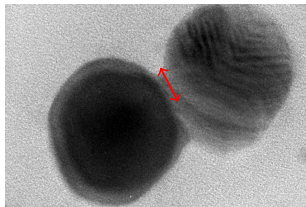
Scaling results – ϕ -kernel 4 – Hazel Hen



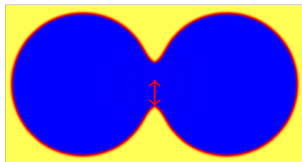
■ preliminary results for ϕ -kernel 4 only

Validation

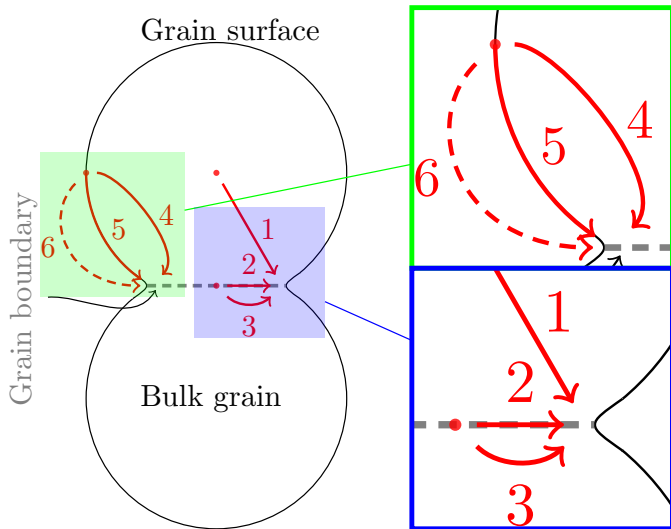
- classical two particle system
- measure parameter: neck radius X
- analytics:
 $X = At^n$, $n \in [0.14, 0.33]$



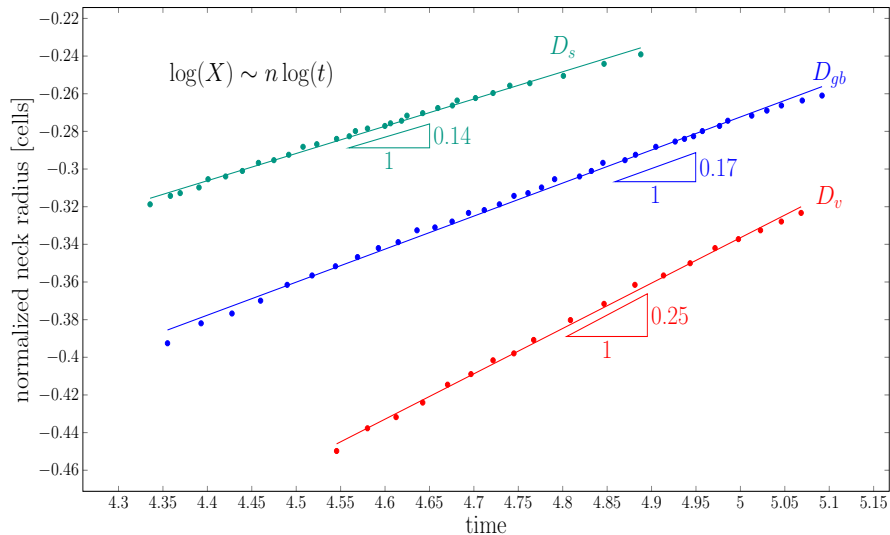
Asoro et al., Acta Materialia 81 (2014): 173-183.



Diffusion paths



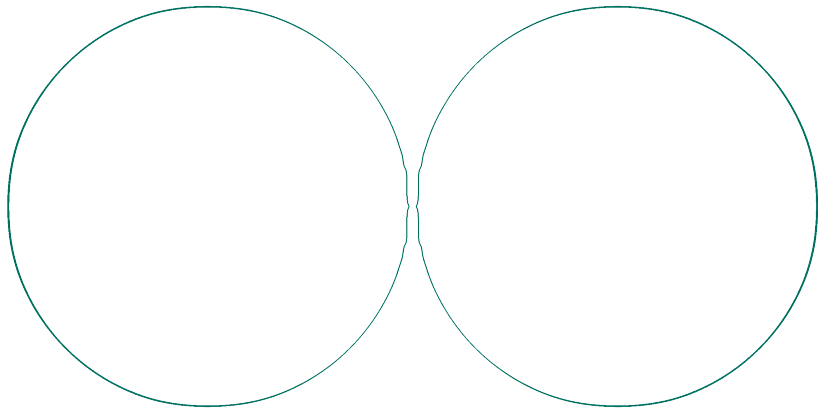
Validation: neck radius



Validation: contour lines

$$\overline{D_s} \quad \overline{D_{gb}} \quad \overline{D_v}$$

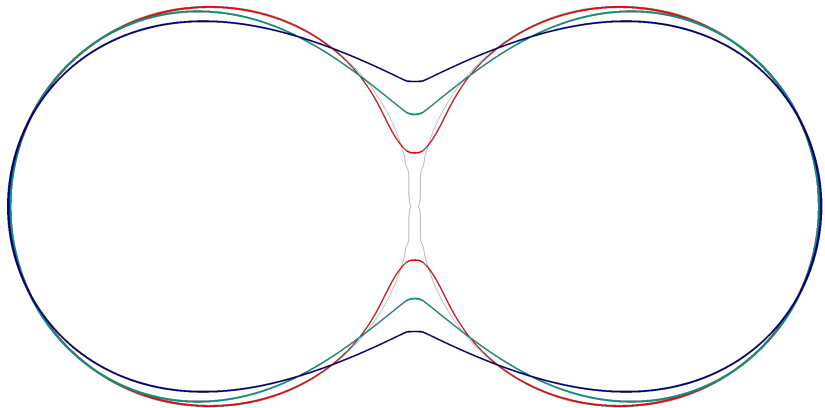
t=0



Validation: contour lines

$\overline{D_s}$ $\overline{D_{gb}}$ $\overline{D_v}$

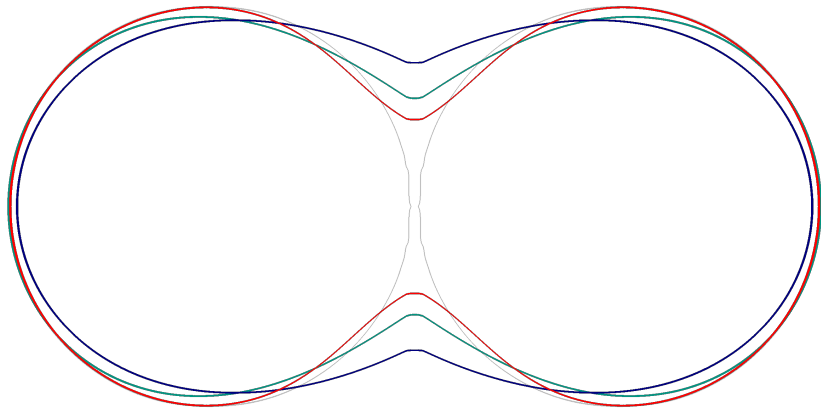
t=1



Validation: contour lines

$\overline{D_s}$ $\overline{D_{gb}}$ $\overline{D_v}$

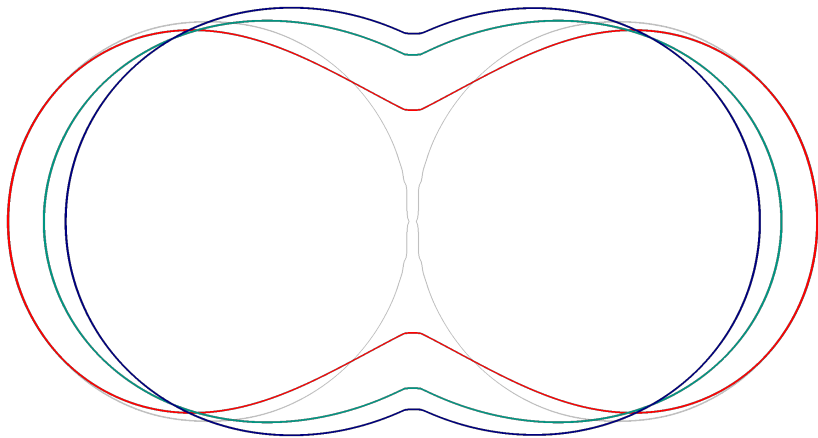
t=2



Validation: contour lines

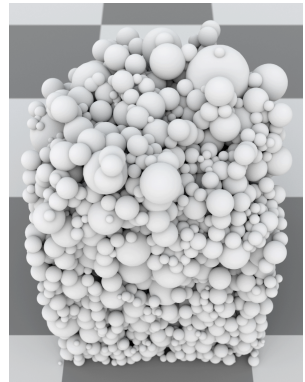
$\overline{D_s}$ $\overline{D_{gb}}$ $\overline{D_v}$

t=3



Green body generator

- generation of packings with defined
 - density
 - particle size distribution
 - particle shapes



Hötzer et al., Forschung Aktuell, Hochschule Karlsruhe, 2016

Video: Simulation of the sinter process

■ 400³ cells, 1333 cores, 24h

Preliminary summary

- efficient calculation of multi phase-field models
- connecting of highly optimized and vectorized kernels
- still optimization potential

Future work

- optimize mapping of LROP cells to vector cells
- optimize mask creation
 - additional field indicating change of mask
 - test only cells ahead of iteration direction
- buffering of parameter vectors depending on mask
- communication hiding for MPI

Thank you for your attention!

Open questions? Ideas? Improvements?

Contact:

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britta.nestler@kit.edu