Time Stamp Synchronization for Event Traces of Large-Scale Message Passing Applications

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Outline

- Introduction
- Event model and replay-based parallel analysis
- Controlled logical clock
- Extended controlled logical clock
- Timestamp synchronization
- Conclusion
- Future work



SCALASCA

- Goal diagnose wait states in MPI applications on largescale systems
- Scalability through parallel analysis of event traces



Wait States in MPI Applications



Non-Synchronized Clocks

- Wait states diagnosis measures temporal displacements between concurrent events
- Problem local processor clocks are often nonsynchronized
 - Clocks may vary in offset and drift
- Present approach linear interpolation
 - Accounts for differences in offset and drift
 - Assumes that drift is not time dependant
- Inaccuracies and changing drifts can still cause violations of the logical event ordering

Synchronization method for violations not already covered by linear interpolation required

Idea

- **Requirement** realistic message passing codes
 - Different modes of communication (P2P & collective)
 - Large numbers of processes
- Build on controlled logical clock by Rolf Rabenseifner
 - Synchronization based on Lamport's logical clock
 - Only P2P communication
 - Sequential program
- Approach
 - Extend controlled logical clock to collective operations
 - Define scalable correction algorithm through parallel replay

Event Model

- Event includes at least timestamp, location and event type
 - Additional information may be supplied depending on event type
- Event type refers to
 - Programming-model independent events
 - MPI-related events
 - Events internal to tracing library
- Event sequence recorded for typical MPI operations





Replay-Based Parallel Analysis

- Parallel analysis scheme
 - SCALASCA toolset



- Originally developed to improve scalability on large-scale systems
- Analyze separate local trace files in parallel
 - Exploits distributed memory & processing capabilities
 - Keeps whole trace in main memory
 - Only process-local information visible to a process
- Parallel replay of target application's communication behavior
 - Parallel traversal of event streams
 - Analyze communication with operation of same type
 - Exchange of required data at synchronization points of target application

Example: Wait at N x N



- Waiting time due to inherent synchronization in N-to-N operations (e.g., MPI_Allreduce)
- Algorithm:
 - Triggered by collective exit event
 - Determine enter events
 - ^o Determine & distribute latest enter event (max-reduction)
 - Calculate & store waiting time

Controlled Logical Clock

- Guarantees Lamport's clock condition
 - Use happened-before relations to synchronize timestamps
 - Send event always earlier than receive event
- Scans event trace for clock condition violations and modifies inexact timestamps
- Stretches process-local time axis in the immediate vicinity of affected event
 - ^o Preserves length of intervals between local events
 - Forward amortization
 - Smoothes discontinuity at affected event
 - Backward amortization



Forward Amortization

Inconsistent event stream

Daniel Becker



• Corrected and forward amortized event stream



Backward Amortization

• Forward amortized event stream



• Forward and backward amortized event stream





Extended Controlled Logical Clock

- Consider single collective operation as composition of many point-to-point communications
- Distinguish between different types
 - 1-to-N
 - N-to-1
 - N-to-N
- Determine send and receive events for each type
- Define happened-before relations based on decomposition of collective operations



Decomposition of Collective Operations

• 1xN: Root sends data to N processes



• Nx1: N processes send data to root



• NxN: N processes send data to N processes





Happened-Before Relation

- Synchronization needs one send event timestamp
- Operation may have multiple send and receive events
- Multiple receives used to synchronize multiple clocks
- Latest send event is the relevant send event
- Example: N-to-1





Forward Amortization

- New timestamp LC' is maximum of
 - Max(send event timestamp + minimum latency)
 - Event timestamp
 - Previous event timestamp + minimum event spacing
 - Previous event timestamp + controlled event spacing



Controller

- Approximates original communication after clock condition violation
- Limits synchronization error
- Bounds propagation during forward amortization
- Requires global view of the trace data

Backward Amortization



- Results of the extended controlled logical clock with jump discontinuities
- Linear interpolation with backwards amortization
- Piecewise linear interpolation with backwards amortization

Amortization interval =
$$\frac{\text{jump}}{\text{accuracy}}$$



Timestamp Synchronization

- Event tracing of applications running on thousands of processes requires scalable synchronization scheme
- Proposed algorithm depends on accuracy of original timestamps
- Two-step synchronization scheme
 - Pre-synchronization
 - · Linear interpolation
 - Parallel post-mortem timestamp synchronization
 - Extended controlled logical clock



Pre-Synchronization

- Account for differences in offset and drift
- Assume that drift is not time dependent
- Offset measurement at program initialization and finalization
 - Among arbitrary chosen master and worker processes
- Linear interpolation between these two points



Parallel Timestamp Synchronization

- Extended controlled logical clock
- Parallel traversal of the event stream
 - Forward amortization
 - Backward amortization
- Exchange required timestamp at synchronization points
- Perform clock correction
- Apply control mechanism after replaying the communication
 - Global view of the trace data
 - Multiple passes until error is below a predefined threshold

Forward Amortization

• Timestamps exchanged depending on the type of operation

Type of operation	timestamp exchanged	MPI function
P2P	timestamp of send event	MPI Send
1-to-N	timestamp of root enter event	MPI Bcast
N-to-1	max(all enter event timestamps)	MPI Reduce
N-to-N	max(all enter event timestamps)	MPI Allreduce



Backward Amortization

• Timestamps exchanged depending on the type of operation

Type of operation	timestamp exchanged	MPI function
P2P	timestamp of receive event	MPI Send
1-to-N	min(all collective exit event timestamps)	MPI Reduce
N-to-1	timestamp of root collective exit event	MPI Bcast
N-to-N	min(all collective exit event timestamps)	MPI Allreduce

Conclusion

- Extended controlled logical clock algorithm takes collective communication semantics into account
 - Defined collective send and receive operations
 - Defined collective happened-before relations
- Parallel implementation design presented using SCALASCA's parallel replay approach
 - Exploits distributed memory & processing capabilities



Future Work

- Finish actual implementation
- Evaluate algorithm using real message passing codes
- Extend algorithm to shared memory programming models
- Extend algorithm to one sided communication





For more information, visit our project home page:

http://www.scalasca.org



