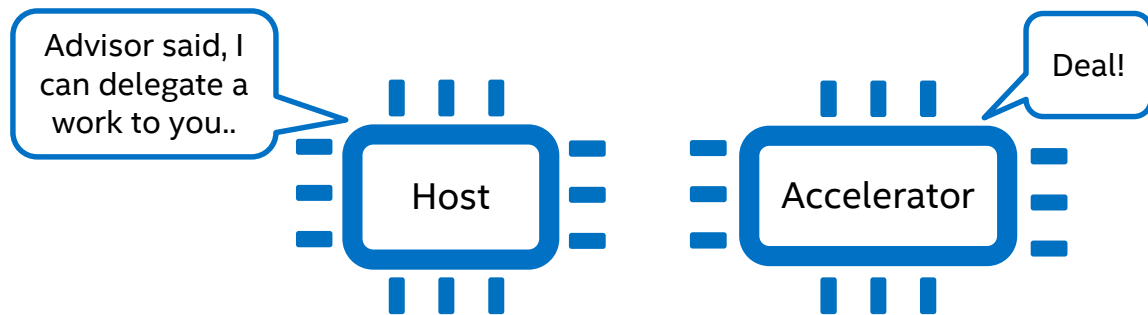




OFFLOAD ADVISOR

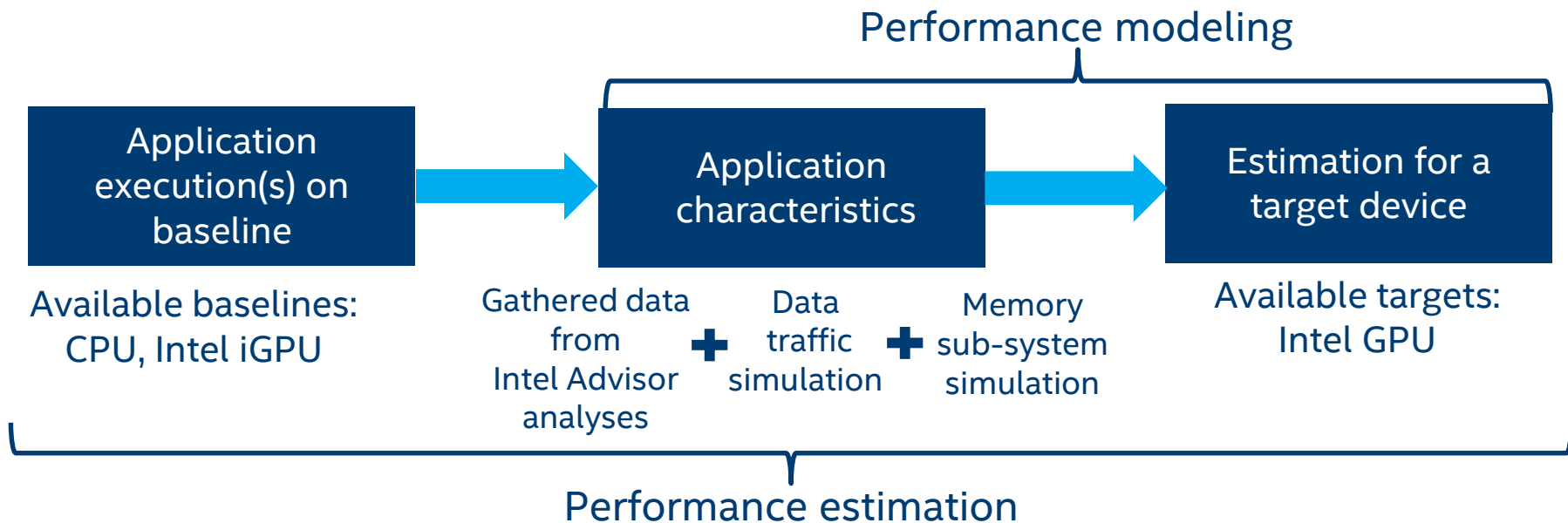
Purpose of Offload Advisor

- Offload Advisor is designed to help users to port their codes to accelerators
 - It can identify the portions of a code that are profitable to be offloaded to an accelerator (e.g. GPU)
 - It can also predict the code's performance if run on an accelerator and lets you experiment with accelerator configuration parameters



How it works

- Offload Advisor reuses Intel Advisor powerful characterization framework
- Also, it is enriched with data traffic, memory sub-system simulation and analytical performance modeling to enable new Offload Advisor workflow

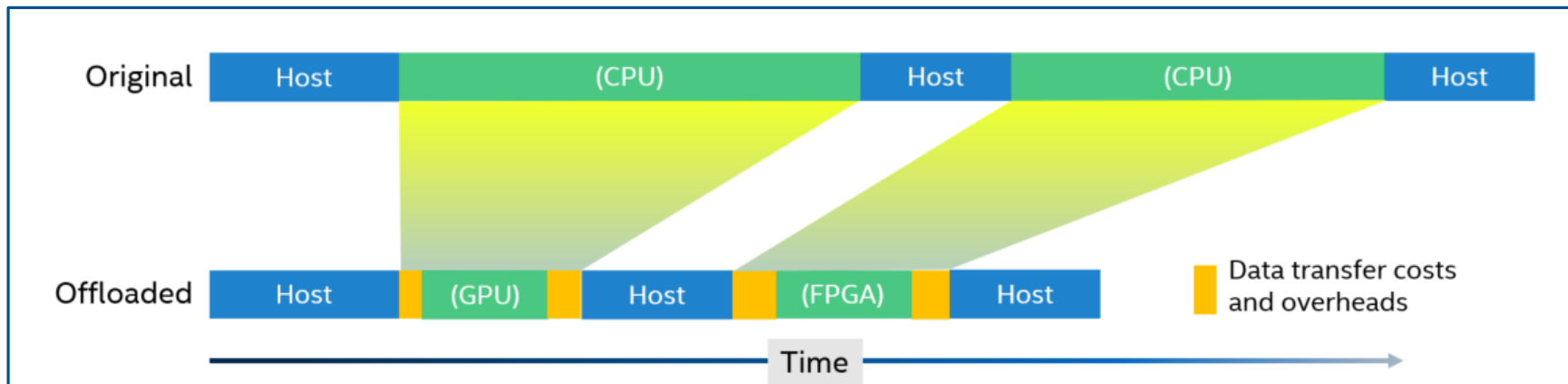


Refer to software.intel.com/articles/optimization-notice for more information regarding performance & optimization choices in Intel software products.

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*Other names and brands may be claimed as the property of others.

How it works (CPU to GPU offloading)

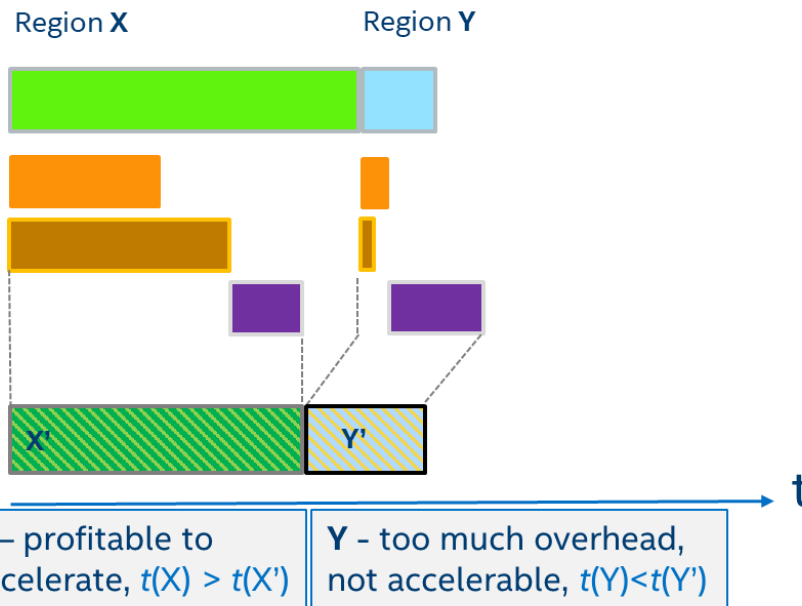


- Data transfer taxes: copy data between CPU and GPU
- Offload taxes: time to place task to GPU task dispatcher

How it works: Region time calculation

Execution time on baseline platform (CPU)

- Execution time on accelerator. Estimate assuming bound exclusively by Compute →
- Execution time on accelerator. Estimate assuming bound exclusively by caches/memory →
- Offload Tax estimate (data transfer + invoke) →



Final estimated time on target device (GPU)

$$t_{\text{region}} = \max(t_{\text{compute}}, t_{\text{memory subsystem}}) + t_{\text{data transfer tax}} + t_{\text{invocation tax}}$$

How it works: Calculation of total time for a loop hierarchy

We minimize the total time spent in a loop hierarchy by varying offload strategies U (offload/non-offload, #threads for each component $loop_i$ of loop nest)

Objective function :

$$T_{all} = \min_{U=\{uf_1, uf_2, \dots\}} \left(\sum_i T_i + t_{data\ transfer} + t_{invoke} + T_{cpu} \right)$$

Reject loop nests for which $T(x86) / T_{all}(x86+\"X\") < 1.0$

$$T_i = \max \begin{cases} T_i^{Comp_only} \\ T_i^{M_k_only} (M_i^k) = \frac{M_i^k}{BW_k} \end{cases}$$

This is effective “balance” (throughput) model

Under algorithmic constraints (Dependencies and TripCount/Granularity)

LAB ACTIVITIES

The Lab Activities

Activity 0: Making the Project on GitLab

Activity 1: Building and running N-body base version

Activity 2: Running performance estimation for the base version

Activity 3: Looking at the estimation results

Activity 4: Rewriting code using DPC++

Activity 5: Building N-body DPC++ version

Activity 6: Comparing base and DPC++ versions

ACTIVITY 0: MAKING THE PROJECT

Activity 0: Make your Project

Sign in Register

Full name
Elizaveta

Username
elizaveta
Username is available.

Email


Email confirmation
eljogar@mail.ru

Password

Minimum length is 8 characters

Register

Navigate to <https://gitlab.boostcode.ru/> ,
Register and Create a project



Create a project
Projects are where you store your code, access issues, wiki and other features of GitLab.

Activity 0: Import Project

Import from: https://gitlab.boostcode.ru/eshulankina/offload_advisor_lab

The screenshot shows the 'Import project' form in GitLab. The 'Import project' button is highlighted with a green box and a blue arrow labeled '1'. Under 'Import project from', the 'git Repo by URL' option is highlighted with a green box and a blue arrow labeled '2'. The 'Git repository URL' field contains the URL 'https://gitlab.boostcode.ru/eshulankina/offload_advisor_lab' and is highlighted with a green box and a blue arrow labeled '3'. Below this are fields for 'Username (optional)' and 'Password (optional)'. A list of instructions is provided below these fields. The 'Project name' field contains 'adv_lab' and is highlighted with a green box and a blue arrow labeled '4'.

Blank project Create from template **Import project** 1

Import project from

GitLab export GitHub Bitbucket Cloud Bitbucket Server **git Repo by URL** 2 Manifest file

Git repository URL 3

`https://gitlab.boostcode.ru/eshulankina/offload_advisor_lab`

Username (optional) Password (optional)

- The repository must be accessible over `http://`, `https://` or `git://`.
- When using the `http://` or `https://` protocols, please provide the exact URL to the repository. HTTP redirects will not be followed.
- If your HTTP repository is not publicly accessible, add your credentials.
- The import will time out after 180 minutes. For repositories that take longer, use a clone/push combination.
- To import an SVN repository, check out [this document](#).

Project name 4

`adv_lab`

ACTIVITY 1: BUILDING N-BODY BASE VERSION

Activity 1: Build & Run

Create your own pipeline to build & run the N-Body base version:

- Add the following jobs to **.gitlab-ci.yml** in your project:

nbody-base-build:

```
stage: build
tags:
  - oneapi
script:
  - make -C ./nbody/base
artifacts:
  paths:
    - ./nbody/base/nbody
```

nbody-base-run:

```
stage: run
tags:
  - oneapi
script:
  - ./nbody/base/nbody $NBODY_ARGS
dependencies:
  - nbody-base-build
```

Activity 1: Check pipeline status

Pipeline Jobs 2

Build

Test

✓ nbody-base-build



✓ nbody-base-run



```
$ ./nbody/base/nbody $NBODY_ARGS
```

```
=====
```

```
Initialize Gravity Simulation
```

```
nPart = 4000; nSteps = 1000; dt = 0.1
```

```
-----
```

s	dt	kenergy	time (s)
---	----	---------	----------

```
-----
```

50	5	66.863	0.67641
----	---	--------	---------

100	10	369.19	0.58348
-----	----	--------	---------

150	15	1089.7	0.58435
-----	----	--------	---------

200	20	3005.8	0.58221
-----	----	--------	---------

250	25	15704	0.5829
-----	----	-------	--------

300	30	10062	0.57951
-----	----	-------	---------

350	35	6497.2	0.57881
-----	----	--------	---------

400	40	5674	0.58026
-----	----	------	---------

450	45	5350.2	0.57886
-----	----	--------	---------

500	50	5019.5	0.58176
-----	----	--------	---------

550	55	5043.5	0.57916
-----	----	--------	---------

600	60	4815.3	0.57909
-----	----	--------	---------

650	65	5010.3	0.5809
-----	----	--------	--------

700	70	4783	0.57874
-----	----	------	---------

750	75	4797.8	0.58029
-----	----	--------	---------

800	80	4987.9	0.57866
-----	----	--------	---------

850	85	4699.8	0.58215
-----	----	--------	---------

900	90	4534	0.57835
-----	----	------	---------

950	95	4907.4	0.58682
-----	----	--------	---------

1000	100	4915.7	0.58003
------	-----	--------	---------

```
# Total Time (s) : 11.713
```

```
=====
```

ACTIVITY 2: RUNNING PERFORMANCE ESTIMATION FOR THE BASE VERSION

How to run Performance Estimation

There are three methods varying in simplicity and flexibility to run performance profiling and performance modeling. Performance profiling and performance modeling are used together to derive performance estimates.

Commands	Notes
Stand-alone run_oa.py script	Most simple and least flexible. Does not support MPI applications.
Combination of collect.py and analyze.py scripts	Somewhat simple and flexible. Does not support MPI applications.
Combination of Advisor Command Line advixe-cl and analyze.py script	Least simple and most flexible. Applicable to MPI applications.

run_oa.py script (most simple)

This is the most simple method.

It automates the process of invoking performance profiling with reasonable pre-defined options, then runs performance modeling on the resulting profiles to generate performance estimates.

- `python $APM/run_oa.py <advisor_results_dir> -o <apm_results_dir> [options] -- <app_binary> [app_options]`

collect.py & analyze.py (simple and flexible)

This is a middle-of-the-road method that is moderately simple and flexible. The collect.py script automates the process of performance profiling and the analyze.py script implements performance modeling.

- `python $APM/collect.py <advisor_results_dir> [options] -- <app_binary> [app_options]`
- `python $APM/analyze.py <advisor_results_dir> -o <apm_results_dir>`

advixe-cl & analyze.py (most flexible)

This is the most flexible method including calling **advixe-cl** (directly invoking the run of Advisor analyses) and a script **analyze.py** that implements performance modeling.

For each required Advisor analysis, you should run **advixe-cl** with the appropriate parameters. After all the information is collected, you should run **analyze.py**.

Example of Survey analysis run:

- `advixe-cl --collect=survey --auto-finalize --stackwalk-mode=online -static-instruction-mix --project-dir=<advisor_results_dir> -- <app_binary> [app_options]`

Activity 2

Add a job to run the performance estimation for the N-Body base version:

- Uncomment the following job:









```
nbody-base-profile:
  stage: profile
  tags:
    - oneapi
  before_script:
    - . . .
  script:
    - mkdir adv_prj

    # Running Offload Advisor
    - advixe-python $APM/collect.py --config=gen9 ./adv_prj -c basic -- ./nbody/base/nbody $NBODY_ARGS
    - advixe-python $APM/analyze.py --config=gen9 --set-parallel=GSimulation.cpp:103,GSimulation.cpp:129 ./adv_prj

    # Running base version of nbody sample
    - . . .
    - ./nbody/base/nbody $NBODY_ARGS | tee -a sample_run.log
    . . .
```

Activity 2: Download artifacts

Changes 1 Pipelines 1

Status	Pipeline	Triggerer	Commit	Stages		
	#218 latest		719899dd Iterations steps for Gitlab-ci.yml	  	 00:05:09  just now	

- Download nbody-base-profile artifacts
- Download nbody-base-build artifacts

ACTIVITY 3: LOOKING AT THE ESTIMATION RESULTS

Activity 3



Intel® Advisor Beta

OFFLOAD ADVISOR

Summary | Offloaded Regions | Non Offloaded Regions | Call Tree | Configuration | Logs

Intel® Advisor Beta, build 604989

Speed Up for Accelerated Code [?](#)

5.1x

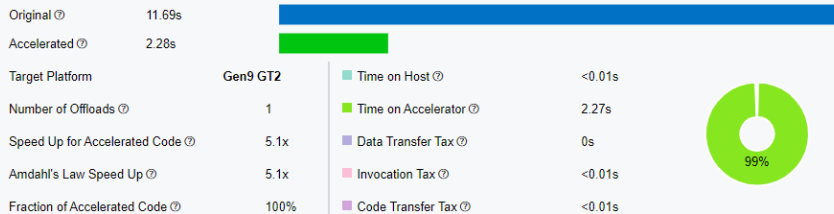
Number of Offloads [?](#)

1

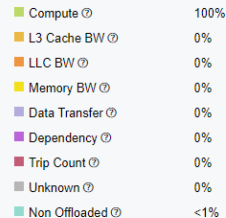
Fraction of Accelerated Code [?](#)

100%

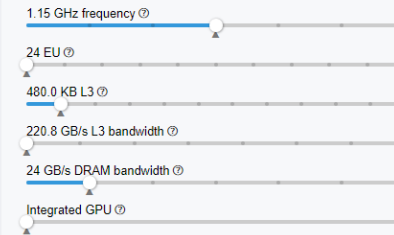
Program metrics [?](#)



Offloads bounded by [?](#)



Gen9 GT2 configuration [?](#)




Top offloaded [?](#)

Location ?	Speed Up ?	Bounded By ?	Data Transfer ?
[loop in GSimulation::start at GSimulation.cpp:103]	5.14x	Compute	0.19MB

Top non offloaded [?](#)

Location ?	Data Transfer ?	Execution Time ?	Why Not Offloaded ?
[loop in GSimulation::start at GSimulation.cpp:100]	0.13MB	CPU 11.69s GPU 433.896	Not profitable: Parallel execution efficiency is limited due to Dependencies
[loop in GSimulation::start at GSimulation.cpp:82]	0.27MB	CPU <0.01s GPU 0.005	Total time is too small for reliable modelling. Use --loop-filter-threshold=0 to model such small offloads.

Activity 3

 Intel® Advisor Beta
OFFLOAD ADVISOR
Summary | [Offloaded Regions](#) | [Non Offloaded Regions](#) | [Call Tree](#) | [Configuration](#) | [Logs](#)

Intel® Advisor Beta, build 604889
Speed Up for Accelerated Code ① **5.1x** | Number of Offloads ② **1** | Fraction of Accelerated Code ③ **100%**

Hierarchy	Loop/Function >			Offload Information >					
	Elapsed Time (s)	Total Time ↓	Dependency Type	Estimated Speed Up	Estimated Time on Accelerator	Total Execution Time by Compute	Total Execution Time by Memory BW Time (s)	Total Execution Time by LLC BW (s)	Total Execution Time by L3 BW (s)
▼ [loop in GSimulation::start at GSimulation.cpp:106]	11.68s	11.678s (99.90%)	Parallel: User	5.14x	2.270s (99.47%)	2.27s	<0.001	<0.001	1.107
[loop in GSimulation::start at GSimulation.cpp:106]	11.68s	11.634s (99.52%)	Parallel: Explicit			2.26s	<0.001	<0.001	1.077

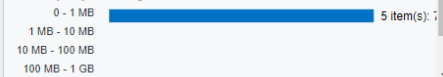
Source Name: [loop in GSimulation::start at GSimulation.cpp:106]

```
97  double tsz = 0;
98
99  const double t0 = time.start();
100  for (int s = 1; s <= get_nsteps(); ++s)
101  {
102      tsz += time.start();
103      for (int i = 0; i < n; i++) // update acceleration
104      {
105          float acc_x = 0.f, acc_y = 0.f, acc_z = 0.f;
106          for (int j = 0; j < n; j++)
107          {
108              float dx, dy, dz;
109              float distanceSqr = 0.f;
110              float distanceTrj = 0.f;
```

Tracked 5 memory objects with 78.1 KB total size

Size ↓	Source Location	Address	Transfer Direction	Type
15.6 KB	vector.tcc:571	0x1c4bd10	shared	
15.6 KB	vector.tcc:571	0x1c4ba0	shared	

Memory object histogram



- 0 - 1 MB: 5 item(s)
- 1 MB - 10 MB
- 10 MB - 100 MB
- 100 MB - 1 GB

ACTIVITY 4: REWRITING CODE USING DPC++

Activity 4

```
1 const double t0 = time.start();
2 for (int s = 1; s <= get_nsteps(); ++s)
3 {
4     ts0 += time.start();
5     for (int i = 0; i < n; i++) // update acceleration
6     {
7         float acc_x = 0.f, acc_y = 0.f, acc_z = 0.f;
8         for (int j = 0; j < n; j++)
9         {
10            . . .
11
12            dx = particles.pos_x[j] - particles.pos_x[i];
13            dy = particles.pos_y[j] - particles.pos_y[i];
14            dz = particles.pos_z[j] - particles.pos_z[i];
15
16            distanceSqr = dx * dx + dy * dy + dz * dz + softeningSquared;
17            distanceInv = 1.0f / sqrtf(distanceSqr);
18
19            acc_x += dx * G * particles.mass[j] * distanceInv * distanceInv * distanceInv;
20            acc_y += dy * G * particles.mass[j] * distanceInv * distanceInv * distanceInv;
21            acc_z += dz * G * particles.mass[j] * distanceInv * distanceInv * distanceInv;
22        }
23        particles.acc_x[i] = acc_x;
24        particles.acc_y[i] = acc_y;
25        particles.acc_z[i] = acc_z;
26    }
27    energy = 0.f;
```

```
1  sycl::default_selector selector;
2  sycl::queue queue(selector, exceptionHandler);
3
4  sycl::buffer<float, 1> posX(particles.pos_x.data(), sycl::range<1>(n));
5  sycl::buffer<float, 1> posY(particles.pos_y.data(), sycl::range<1>(n));
6  sycl::buffer<float, 1> posZ(particles.pos_z.data(), sycl::range<1>(n));
7  sycl::buffer<float, 1> velX(particles.vel_x.data(), sycl::range<1>(n));
8  . . .
9  sycl::buffer<float, 1> mass(particles.mass.data(), sycl::range<1>(n));
10 sycl::buffer<float, 1> energy(_energy, sycl::range<1>(n));
11
12 const double t0 = time.start();
13 for (int s = 1; s <= get_nsteps(); ++s)
14 {
15     ts0 += time.start();
16     queue.submit([&](sycl::handler &cgh) {
17         auto posXBuff = posX.get_access<sycl::access::mode::read>(cgh);
18         auto posYBuff = posY.get_access<sycl::access::mode::read>(cgh);
19         auto posZBuff = posZ.get_access<sycl::access::mode::read>(cgh);
20         auto massBuff = mass.get_access<sycl::access::mode::read>(cgh);
21         auto accXBuff = accX.get_access<sycl::access::mode::write>(cgh);
22         auto accYBuff = accY.get_access<sycl::access::mode::write>(cgh);
23         auto accZBuff = accZ.get_access<sycl::access::mode::write>(cgh);
24         cgh.parallel_for<class kernel1>(sycl::range<1>(n), [=](sycl::id<1> index) {
25             int i = index.get(0);
26             float acc_x = 0.f, acc_y = 0.f, acc_z = 0.f;
27             for (int j = 0; j < n; j++)
28             {
29                 . . .
30
31                 dx = posXBuff[j] - posXBuff[i];
32                 dy = posYBuff[j] - posYBuff[i];
33                 dz = posZBuff[j] - posZBuff[i];
34
35                 distanceSqr = dx * dx + dy * dy + dz * dz + softeningSquared;
36                 distanceInv = 1.0f / sycl::sqrt(distanceSqr);
37
38                 acc_x += dx * G * massBuff[j] * distanceInv * distanceInv * distanceInv;
39                 acc_y += dy * G * massBuff[j] * distanceInv * distanceInv * distanceInv;
40                 acc_z += dz * G * massBuff[j] * distanceInv * distanceInv * distanceInv;
41             }
42             accXBuff[i] = acc_x;
43             accYBuff[i] = acc_y;
44             accZBuff[i] = acc_z;
45         });
46     }).wait_and_throw();
```

ACTIVITY 5: BUILDING N-BODY DPC++ VERSION

Activity 5

- Disable **nbody-base-run** and **nbody-base-profile** jobs (comment them)
- Add the following jobs to **.gitlab-ci.yml** in your project:

```
nbody-dpcpp-build:  
  stage: build  
  tags:  
    - oneapi  
  script:  
    - make -C ./nbody/dpcpp  
  artifacts:  
    paths:  
      - ./nbody/dpcpp/nbody
```

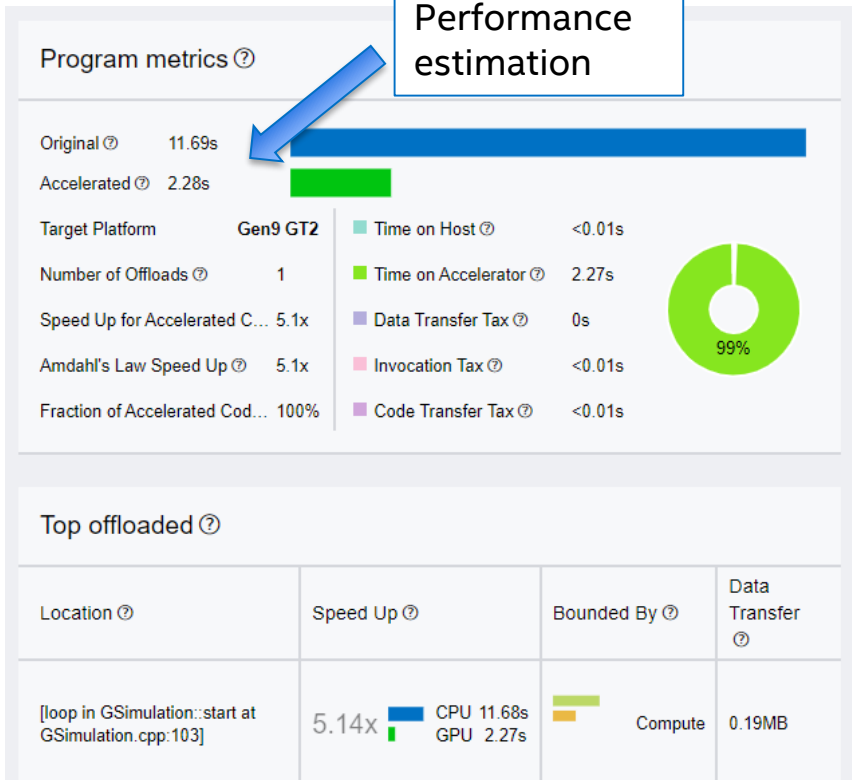
```
nbody-run:  
  stage: test  
  tags:  
    - oneapi  
  script:  
    - ./nbody/base/nbody $NBODY_ARGS  
    - ./nbody/dpcpp/nbody $NBODY_ARGS  
  dependencies:  
    - nbody-base-build  
    - nbody-dpcpp-build
```

ACTIVITY 6: COMPARING BASE AND DPC++ VERSIONS

Activity 6

Actual runs

Performance estimation



\$. /nbody/base/nbody \$NBODY_ARGS

Initialize Gravity Simulation
nPart = 4000; nSteps = 1000; dt = 0.1

s dt kenergy time (s)

s	dt	kenergy	time (s)
50	5	66.863	0.67641
100	10	369.19	0.58348
150	15	1089.7	0.58435
200	20	3005.8	0.58221
250	25	15704	0.5829
300	30	10062	0.57951
350	35	6497.2	0.57881
400	40	5674	0.58026
450	45	5350.2	0.57886
500	50	5019.5	0.58176
550	55	5043.5	0.57916
600	60	4815.3	0.57909
650	65	5010.3	0.5809
700	70	4783	0.57874
750	75	4797.8	0.58029
800	80	4987.9	0.57866
850	85	4699.8	0.58215
900	90	4534	0.57835
950	95	4907.4	0.58682
1000	100	4915.7	0.58003

Total Time (s) : 11.713

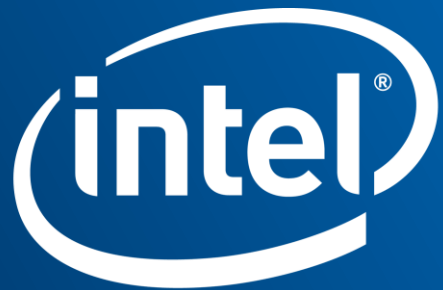
\$. /nbody/dpcpp/nbody \$NBODY_ARGS

Initialize Gravity Simulation
nPart = 4000; nSteps = 1000; dt = 0.1

s dt kenergy time (s)

s	dt	kenergy	time (s)
50	5	66.863	0.345
100	10	369.19	0.10216
150	15	1089.7	0.10016
200	20	3005.8	0.10037
250	25	15704	0.10028
300	30	10062	0.10016
350	35	6497.2	0.10043
400	40	5674	0.10045
450	45	5350.2	0.10023
500	50	5019.5	0.10045
550	55	5043.5	0.099716
600	60	4815.3	0.10027
650	65	5010.3	0.10033
700	70	4783	0.1006
750	75	4797.8	0.1004
800	80	4987.9	0.10037
850	85	4699.8	0.10162
900	90	4533.9	0.099533
950	95	4907.5	0.1011
1000	100	4915.7	0.10097

Total Time (s) : 2.2563



Software

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Notice revision #20110804